

# IP

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## Design and Implementation of Active Measurement Tool for One-way IP Performance Measurement

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IP  
Global Positioning System(GPS)      Micro-second  
가

IP

1.

[1].

가

IETF IPPM(IP Performance Metrics) (WG)  
(Metric)

[2]. (one-way  
delay), (delay variation),  
(one-way packet loss), (packet  
loss pattern) [3,4,5].

. 2

. 3

. 4

[6,7,8].

## 2. Active Measurement Tool (AMT)

AMT IETF IPPM  
WG  
(Infrastructure) AMT  
FreeBSD UNIX PC  
MySQL

2.1 GPS

RTT

가

(Measurement System)

1 GPS

(Control System)

GPS

2

가

AMT

GPS

1 AMT

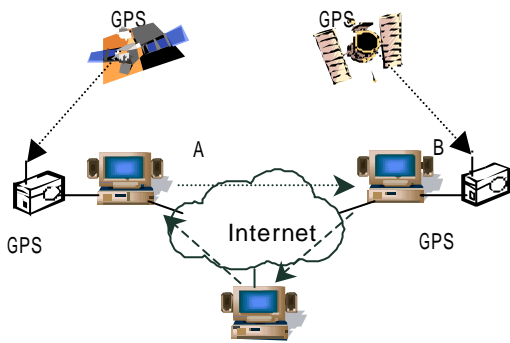
Motorola Oncore Remote Antenna, Oncore GPS Receiver(UT) GPS

[9]. 가

Network Time Protocol

ntpd

[10].



1.

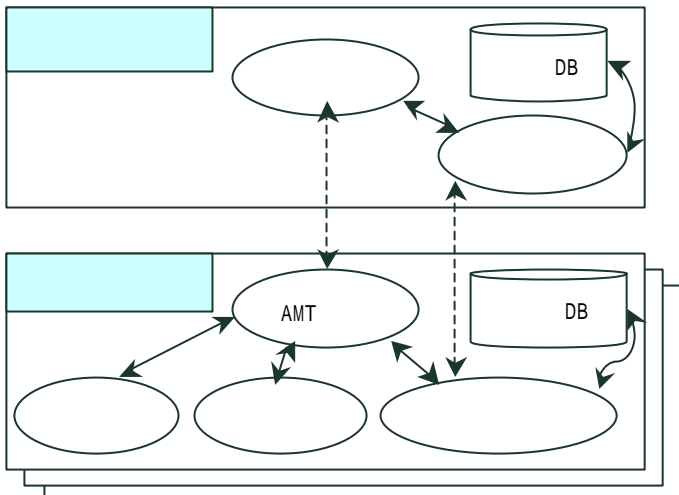
2.2

가 IP

가

[11,12].

2.3 AMT  
AMT



2. AMT

(Control System)

2.3.1

(Control Server)

1)

AMT

2)

(Storage Server)

(Local DB)

(Delivery Agent)

2.3.2

(Measurement System)

1) AMT

(AMT Daemon)

AMT

AMT

가

(AMT Sender)

, AMT  
(AMT Receiver)

2)

(AMT Sender)

AMT

가

(Pseudo-random number generator)

(Poisson Process)

3)

(AMT Receiver)

<

IP

>

IP

(Delivery Agent)

AMT

3.

3.1

KORNET  
1(MS1)

AMT 가  
IP

147.46.14.69

2(MS2) IP

203.232.127.20

KORNET

3.2 2000 11 28 0 2000 11 28

12  
 Lambda가 2 Poisson  
 3 MS1 MS2 (Delay1)  
 4 MS2 MS1  
 (Delay2) X  
 5 Y  
 1 (us) 가  
 ; (a) Minimum delay, (b) 95<sup>th</sup> percentile, (c)  
 Maximum delay.  
 5  
 Percentile 가 가

( 3, 4) 95<sup>th</sup> percentile  
 MS1  
 MS2 Path Delay1 MS2  
 MS1 Path Delay2  
 , MS1 MS2 Path가 MS2 MS1 Path  
 Load가 가 MS1  
 MS2 Path  
 Routing 가  
 Ping RTT

4.

(Metric)

AMT(Active Measurement Tool)

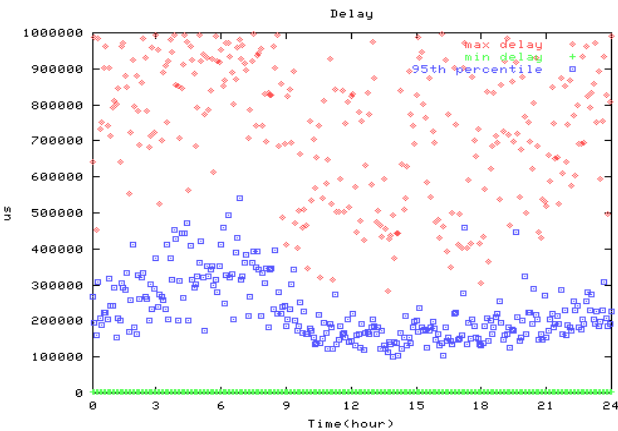
KORNET

AMT

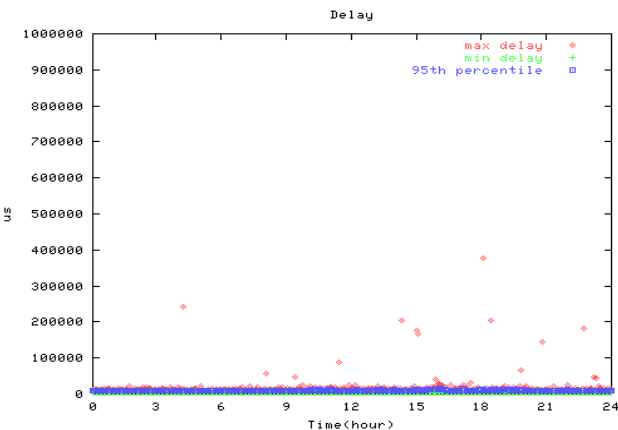
AMT

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3. MS1 MS2 One-way Delay



4. MS2 MS1 One-way Delay

2001

21

가