

FootprintID: Indoor Pedestrian Identification through Ambient Structural Vibration Sensing

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Outline

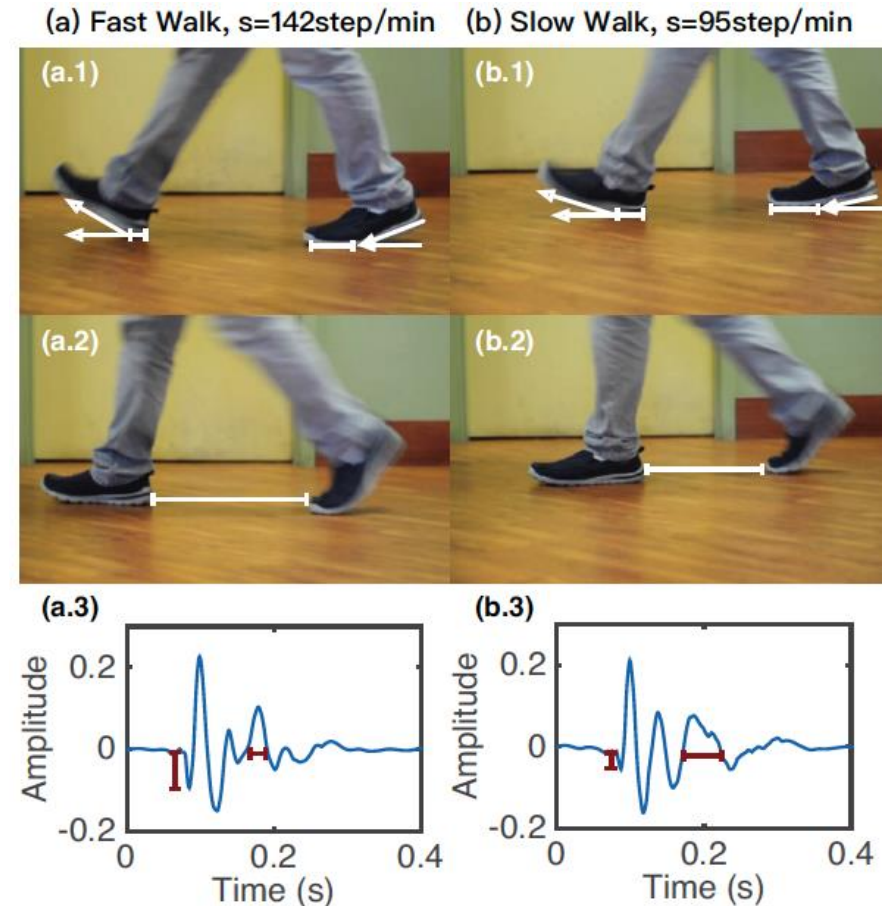
- Introduction
- System Design and details
- Evaluation
- Conclusion

Introduction: *FootprintID*

- Identify a pedestrian through the footstep-induced vibration on the floor
 - *The unique walking patterns induce distinguishable vibration*
 - It should consider the sensitivity to changing walking conditions including walking speed and stepping locations
- Present a novel algorithm to infer pedestrian identity
 - Select step signals based on stepping location
 - Select supervised or transductive classifiers based on walking speed
 - Apply RTSVM and ITSVM when the tested walking speeds vary from those in the labeled training set

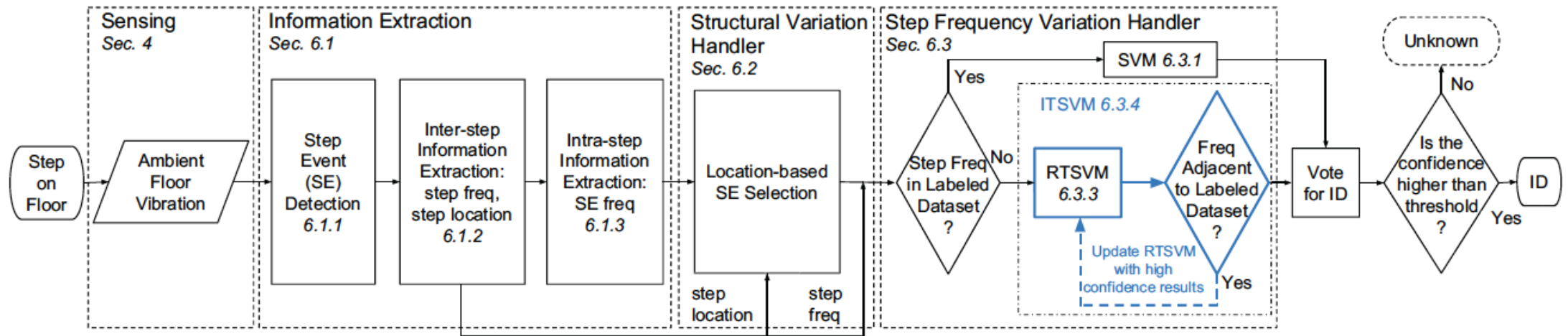
Background: Vibration from Gaits

- Why people have different gaits
 - Gait describes a subject's walking pattern including limb locomotion and neurological control
- Why the location and frequency of the steps affect the sensing signal
 - Vibration signal waveforms can be different due to material heterogeneity and structural layout
 - The higher the step frequency, the longer the step length, and the faster the walking speed



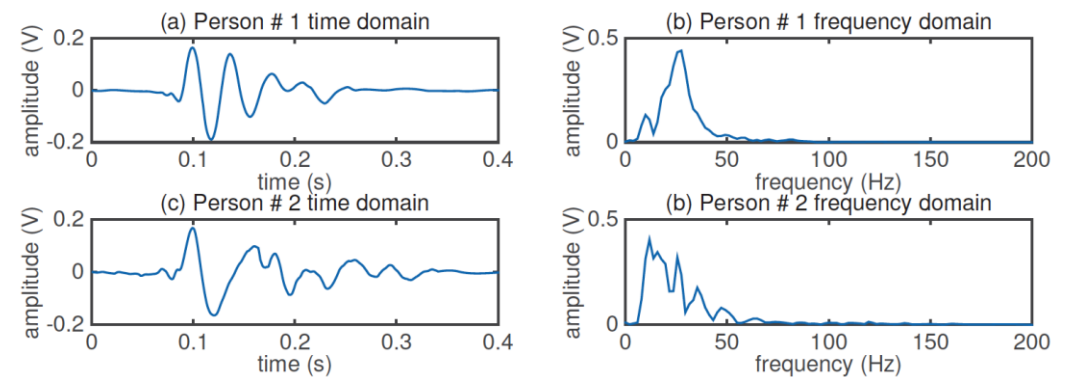
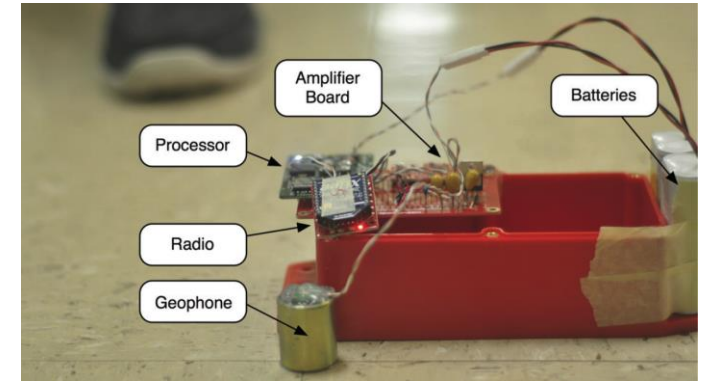
System Overview

- Identify pedestrians by classifying **gait patterns**
 - Gait patterns would be distinguishable based on each person's walking habits
- Need to overcome **variations due to structural difference of each floor and step frequency variation** by walking speed



1. Data Sensing

- Place a sensing unit on the floor and fix geophone to preserve high-frequency signals
- Convert the velocity of the monitored surface to voltage by geophone
- Convert the signal into a digitized signal with a 10-bit ADC module sampled at 1000 Hz
- Observe a clear difference in both time and frequency domains of different gaits from two pedestrians

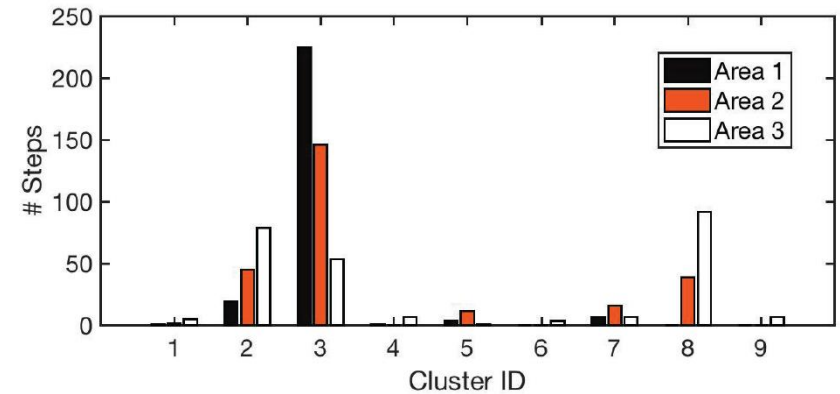


2. Information Extraction

- Conduct feature extraction to represent a person's footstep effectively
- Step Events Detection → *threshold* = $\mu_{wse} + 3\sigma_{wse}$
 - Form a Step Event by finding consecutive candidate windows which have higher energy value over the threshold
- Inter-footstep step frequency and relative location
 - Estimate the average time interval between consecutive Step Events excepting the highest and lowest K values
- Intra-footstep frequency
 - Normalize the signal energy to remove the footstep-sensor distance difference

3. Structural Vibration Handler

- Should select SEs that are from approximately the same area from each trace
 - Even similar foot strikes are only comparable when they are from the same area
- Infer step location based on the SE of the closest area to the sensor to overcome structural variation
 - Calculate the average value of SE energy using a sliding window to smooth the trend change
 - Select the peak of the sequence of calculated value as the closest area to the sensor



4. Step Frequency Variation Handler

- Aim to acquire better accuracy, even though a large amount of labeled training data is not collected from diverse walking speeds

→ Accuracy vs. Performance

- Choose between supervised learning and transductive learning based on the detected footstep step frequency
 - Apply the supervised learning model (SVM) directly for a dataset with step frequencies in the labeled training data
 - Use an iterative transductive support vector machine (ITSVM) algorithm if the step frequency is not in the labeled training data

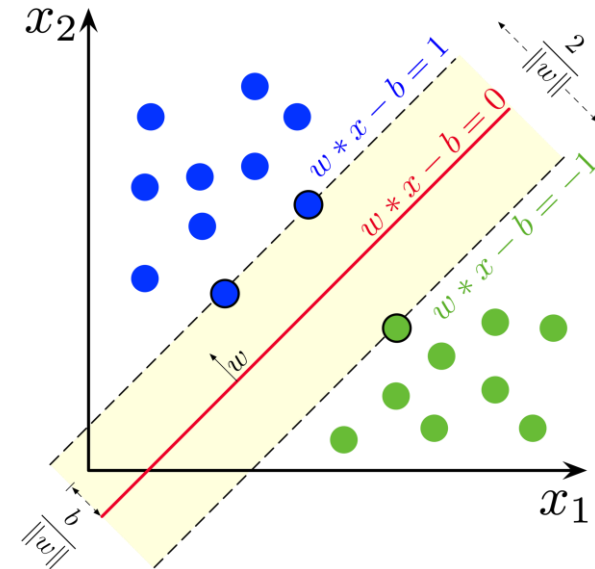
Support Vector Machine (SVM)

- Find the maximum-margin hyperplane w by minimizing the loss function, given two-class training data

$$\min_{w, b} \quad \frac{1}{2} \|w\|^2 + C \sum_{q=1}^l \max(1 - y_q(w^T \phi(x_q) + b), 0),$$

- Balance regularization term and training losses
- Achieve high accuracy in identifying the participants when they walk at a specific speed during a short amount of time

→ How about different step frequency?



Transductive SVM (TSVM)

- Find the maximum-margin hyperplane w and bias term b by minimizing the following loss function, given two-class training data and **unlabeled data**

$$\min_{w,b} \quad \frac{1}{2} \|w\|^2 + C_1 \sum_{q=1}^l \max(1 - y_q (w^T \phi(x_q) + b), 0) \\ + C_2 \sum_{q=l+1}^{l+u} \max(1 - |w^T \phi(x_q) + b|, 0),$$

- Tend to find boundaries in regions where there is less labeled and unlabeled data (low-density separation method)

→ **How about reducing irrelevant unlabeled data?**

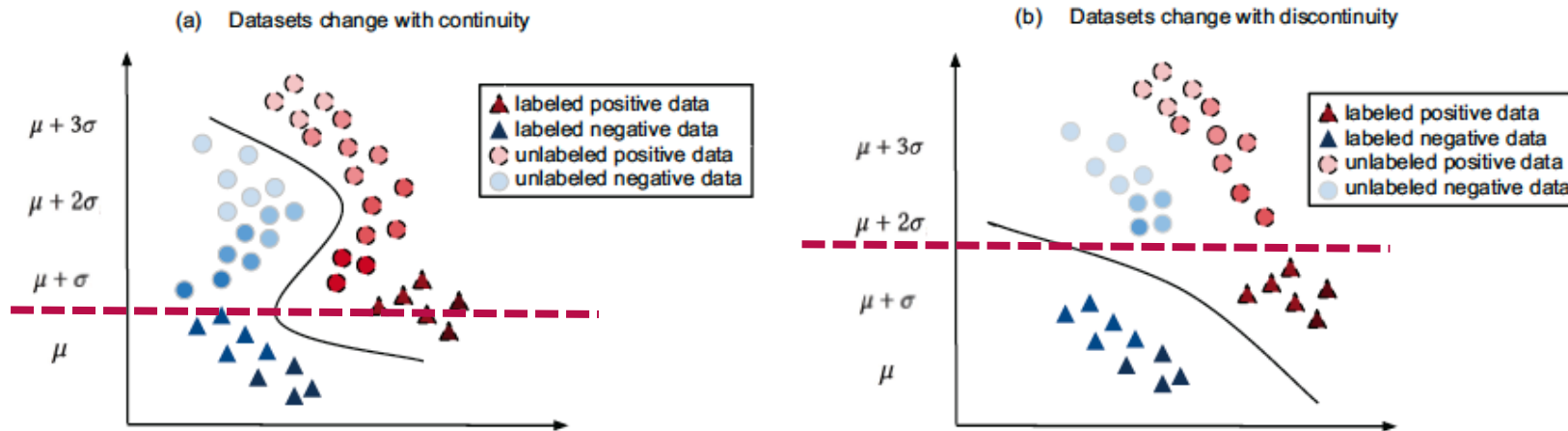
Refined Transductive SVM (RTSVM)

- Need to refine the relevant unlabeled data for the training of each binary TSVM to overcome the irrelevant unlabeled data problem → *k-class problem*
 - A selected unlabeled dataset leads to a faster training speed
- Utilize supervised SVM to pre-select unlabeled SEs, which are most likely to be class i or j
 - Use multi-class SVM with labeled data to predict the identity of all unlabeled SEs
 - Calculate the most frequently appearing class in each trace as the class of the trace and use SEs for the binary TSVM modeling

→ How about various step frequencies?

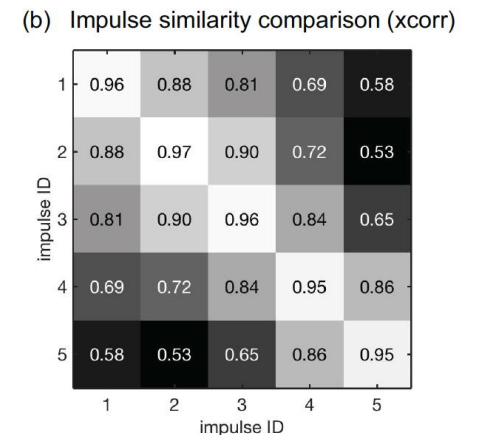
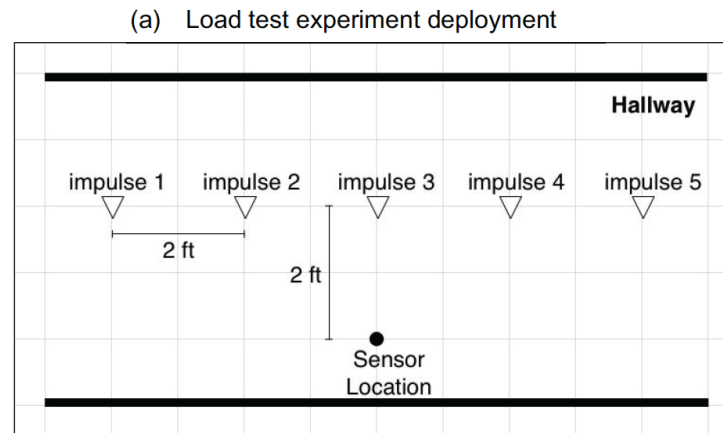
Iterative Transductive SVM (ITSVM)

- Train multi-class TSVM model in an iterative way
 - Label some unlabeled data in the frequency of $\mu \pm \sigma$ to increase the size of the 'labeled' dataset
 - Construct multi-class RTSVM with the test data with step frequencies of $\mu \pm 2\sigma$ and $\mu \pm 3\sigma$ based on the updated labeled dataset



Load Test

- Figure out the reasonable threshold to cluster the Step Events indicating negligible differences caused by structural variation
 - The load test uses ball drops to understand structural vibration without human behavior randomness
 - The structural variation effects on footstep induced vibration data can be clearly observed in the area monitored by one sensor

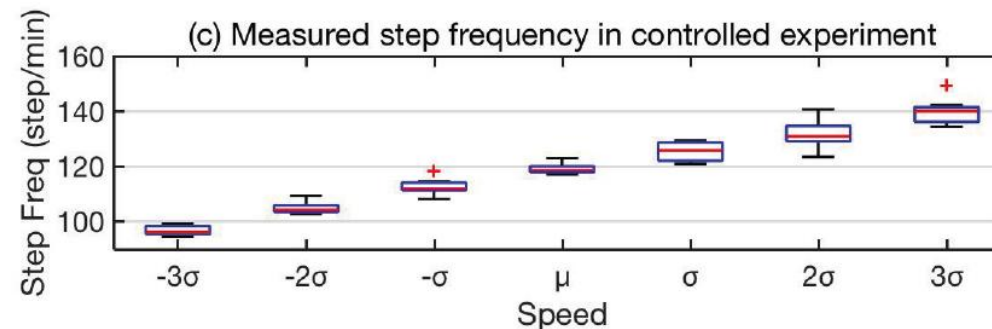


Controlled Human Test

- Collect data for seven controlled step frequencies with metronome beats

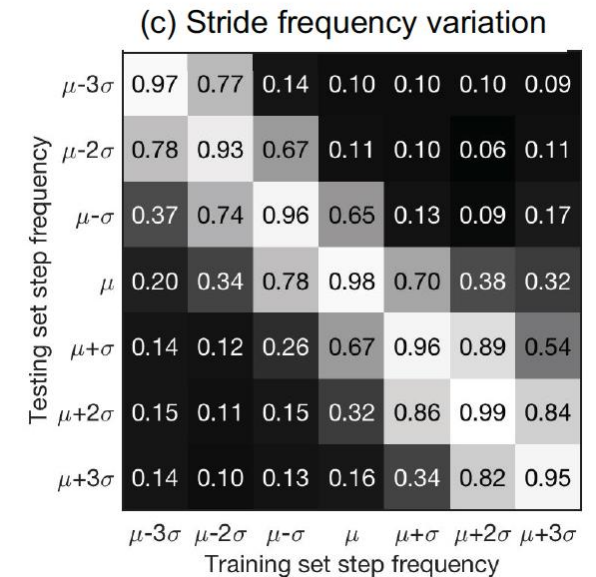
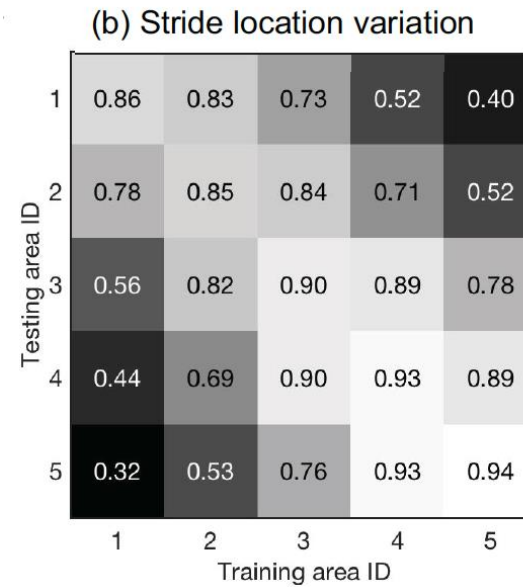
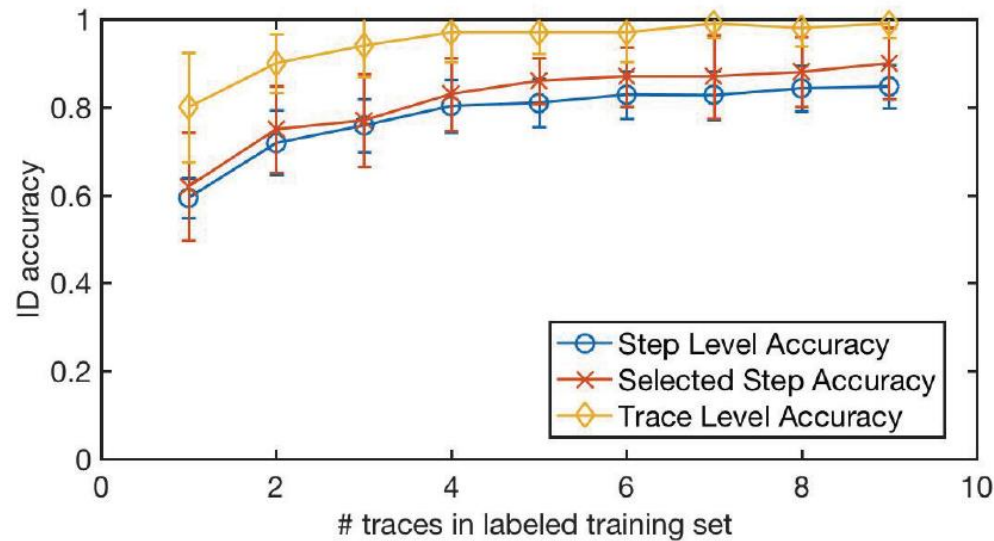
Gender \ Step Freq	$\mu - 3\sigma$	$\mu - 2\sigma$	$\mu - \sigma$	μ	$\mu + \sigma$	$\mu + 2\sigma$	$\mu + 3\sigma$
Male	95	103	111	119	127	134	142
Female	98	107	116	125	134	143	152

- Consider various step frequency due to randomness in human behavior
 - Check that the variations are small enough and each level is clearly distinguishable



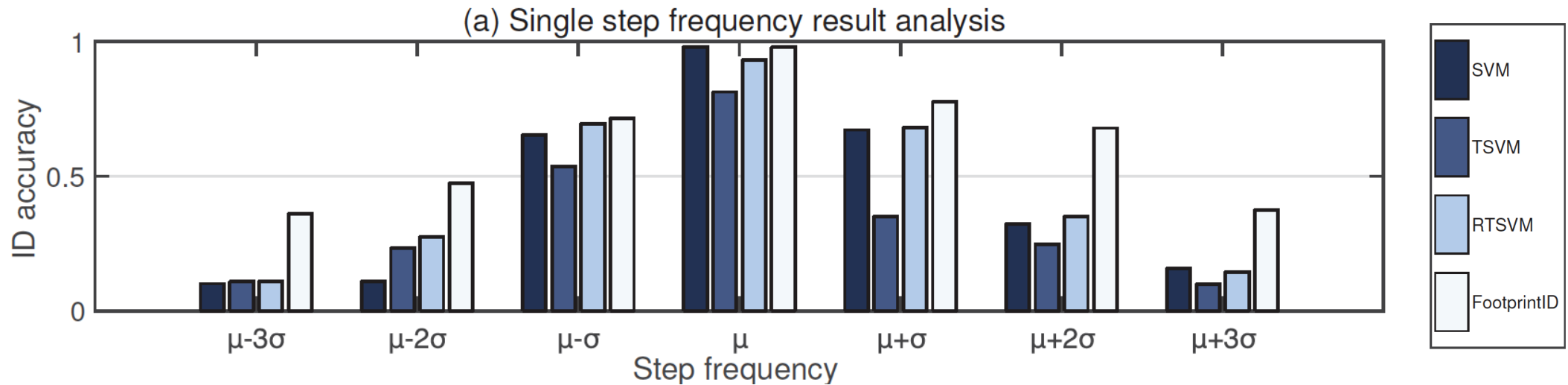
Evaluation of System Factors

- Compare the effect of the amount of labeled training dataset, step location, and step frequency to identification accuracy



Algorithm Analysis

- Evaluate the identification accuracy and runtime for scalability using SVM, TSVM, RTSVM, and ITSVM

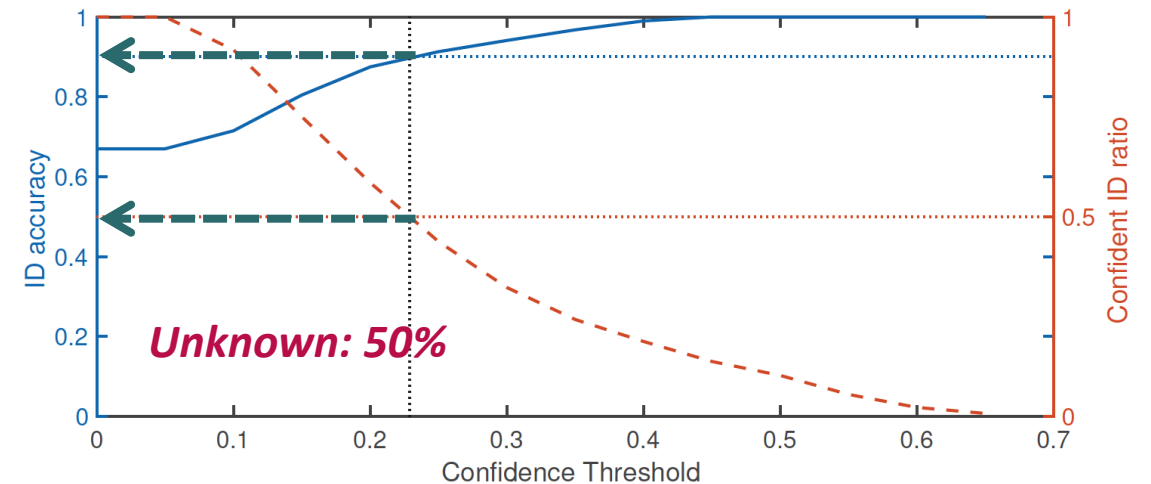


Algorithms	SVM (train on μ)	SVM (train on $\mu \pm 3\sigma$)	TSVM	RTSVM	ITSVM (FootprintID)
Runtime Avg. (s)	0.8724	9.7886	382.4303	74.7586	218.9920
Runtime Std. (s)	0.0496	0.9174	94.8886	8.3837	18.9385

Uncontrolled Experiments

- Evaluate the system based on pedestrian's natural walking form
- Achieve the best accuracy due to the higher accuracy on the low step frequency data in case of ITSVM
- Improve identification accuracy from 67% to 90% when threshold discards half of the data

Models	SVM	TSVM	RTSVM	ITSVM (FootprintID)
labeled: μ , unlabeled: $\mu \pm \sigma$, $\mu \pm 2\sigma$, $\mu \pm 3\sigma$, uncontrolled	56%	52%	52%	67%
labeled: μ , unlabeled: $\mu \pm \sigma$, $\mu \pm 2\sigma$, $\mu \pm 3\sigma$	56%	54%	51%	67%
labeled: μ , unlabeled: uncontrolled	50%	22%	22%	45%



Conclusion

- Present the **FootprintID** system which identifies pedestrians using footstep induced structural vibrations
- Characterize the **variation of footstep** induced structural vibration signals and design **ITSVM learning algorithm**
- Identify correct pedestrians up to **96% accuracy** by ITSVM with the average step frequency μ dataset as training data
- Demonstrate to improve **1.5X identification accuracy in uncontrolled experiments** based on ITSVM

Thank you