DOVE: Data Offloading through Spatio-temporal Rendezvous in Vehicular Networks

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Outline

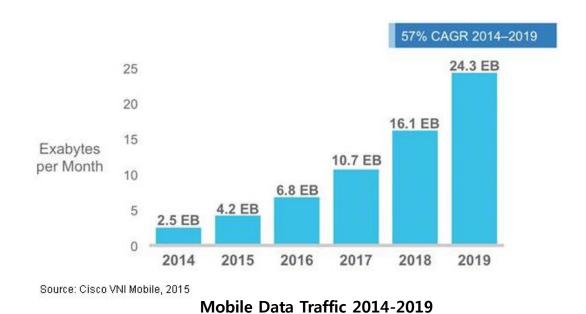
- Motivation
- DOVE framework & operations
- DOVE algorithm
- Evaluation
- Conclusion

Background

- Vehicular networks
 - Promising research area to support the driving safety
 - i.e., vehicle collision avoidance
- Communication module for vehicular networks
 - Dedicated Short Range Communications (DSRC)
 - IEEE 802.11p (WAVE)
 - Embedded cellular connectivity systems
 - GM, Toyota, Hyundai...
- In-vehicle data services
 - By the help of DSRC and cellular connectivity system
 - Real time services (e.g., road traffic information)
 - Software update for car system
 - RSS services (as non-real time applications) for car dash screen
 - E.g., news headlines and audio/video clips for entertainment

Motivation (1/3)

- Traffic explosion in mobile environments
 - The increasing mobile traffic is becoming a serious concern for mobile network providers
 - In-vehicle data service will worsen the problem



Motivation (2/3)

- How to reduce the mobile traffic?
 - Data offloading
 - One of solutions to resolve traffic explosion problem
 - Offloading the traffic from cellular networks to other networks
 - E.g., WiFi hotspots, femtocells
 - Reducing redundant traffic
 - Request for some popular videos account for the majority of all the requests [1]
 - A significant amount of cellular traffic is redundant [2]
 - → We focus on the data offloading for redundant traffic caused by in-vehicle data services

^[1] M. Cha, H. Kwak, P. Rodriguez, Y.-Y. Ahn, and S. Moon, "I Tube, You Tube, Everybody Tubes: Analyzing the Worlds Largest User Generated Content Video System," in Proc. of ACM IMC, 2007.

^[2] S. Woo, E. Jeong, S. Park, J. Lee, S. Ihm, and K. Park, "Comparison of caching strategies in modern cellular backhaul networks," in Proc. of ACM MobiSys, 2013.

Motivation (3/3)

- Research question?
 - How to design an offloading framework utilizing components of vehicular networks for <u>delay-insensitive data services</u>, while <u>minimizing the usage of cellular links</u>
- Let's focus on features of vehicular networks
 - Vehicles
 - Multiple communication devices (DSRC, 3G, 4G-LTE)
 - GPS navigator, storage
 - Predictable mobility
 - Constrained roadways, navigation paths (vehicle trajectories)
 - Vehicular infrastructure
 - Relay Nodes (RNs) can be used for data offloading

Proposed Idea Overview (1/2)

Target scenario

 Reducing cellular traffic for vehicles by offloading the redundant traffic (of popular files) to vehicular networks

Target content files

- Popular files for delay-insensitive in-vehicle data services
 - Update files for software in car system
 - Popular multimedia files (e.g., headline news, music files, and YouTube video clips)

Goal

- Selecting effective offloading positions (OPs) that minimize the aggregated usage of cellular links for vehicles
 - i.e., the amount of data downloaded through cellular networks

Proposed Idea Overview (2/2)

- DOVE: data offloading through vehicular networks
 - Using vehicle infrastructures (i.e., RNs) as <u>offloading positions</u>
 (OPs) for offloading purposes
 - Offloading the cellular traffic to OPs (in vehicular networks) by exploiting vehicle trajectories

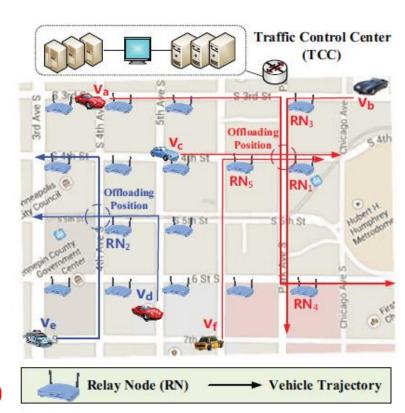
Contributions

- Proposing a <u>data offloading framework (called DOVE)</u> by using the components of vehicular networks
- Formulating the selection of OPs as a set-covering problem
- Proposing a <u>time-prediction based set-covering algorithm</u> (called <u>DOVE algorithm</u>) to select OPs

DOVE Framework (1/2)

DOVE components

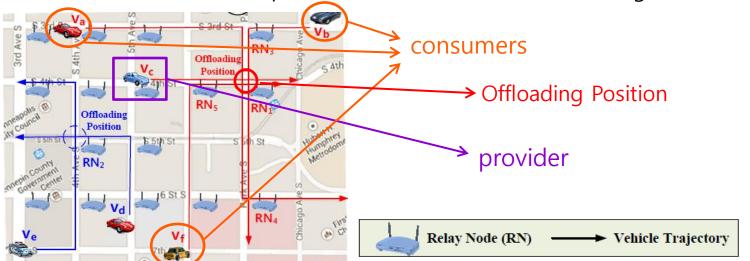
- Traffic control center (TCC)
 - Traffic management node
 - Maintaining vehicle trajectories
 - Collecting content requests from vehicles
- Relay node (RN)
 - Wireless packet holder for the reliable forwarding
 - Equipped with DSRC, storage
 - Usually deployed in vehicular networks for the driving safety
 - Role of offloading position (OP)
- Vehicles
 - GPS navigator, DSRC, cellular communication device



DOVE Framework (2/2)

- Concept of offloading in DOVE
 - Given trajectories, finds RNs where trajectories are overlapped
 - Candidates for OPs
 - Selects appropriate OPs (i.e., RN) for data offloading
 - Decides provider and consumers
 - Provider
 - downloads the file using cellular links and stores it into the RN
 - Consumers

- retrieve the requested file from the <u>RN</u> without using cellular links



DOVE Operation

- Traffic control center (TCC)
 - 1. TCC collects the content requests and the trajectory from each vehicle
 - 2. TCC decides the OPs (i.e., selected RNs) and provider for data offloading
 - Using <u>DOVE algorithm</u>
 - 3. TCC sends the offloading information to vehicles

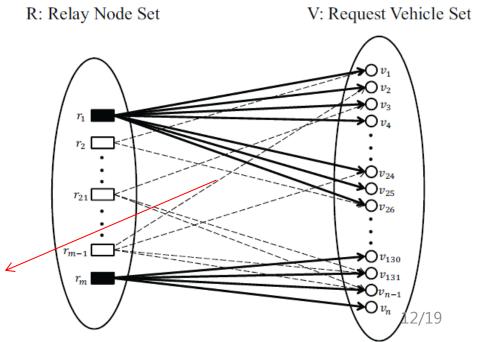
Vehicles

- 4. Vehicles obtain the offloading information from TCC
- 5. Providers (first arrival vehicles at the RN) download a file using cellular traffic and put the file at the RN
- 6. Consumers can retrieve the file from RNs and thus they can reduce the cellular traffic

DOVE Algorithm (1/3)

- Formulate <u>selection of RNs</u> as a <u>set-covering problem</u>
 - Definition
 - V : set of request vehicles requesting the same content
 - R : set of relay nodes (RNs) where trajectories of vehicles in V are overlapped
 - S_i: set of request vehicles covered by an RN_i
 - 'cover' means that vehicles in S_i can get the content from the RN_i
 - F: family of the subsets of V
 - Goal
 - Finding a minimum set-cover C* of RNs as follows:
 - C* ← arg $\min_{C \subseteq F} |C|$ where V = $\bigcup_{S_i \in C} S_i$

A line means that the vehicle will traverse the RN



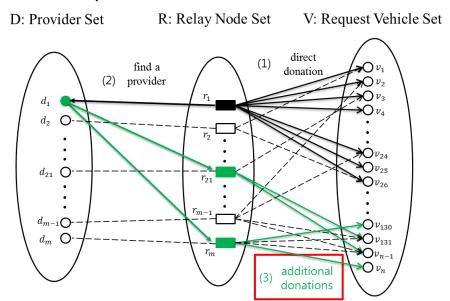
DOVE Algorithm (2/3)

- DOVE algorithm (RN selection)
 - Using greedy approach
 - known as the best possible polynomial time approximation algorithm
 - Time-prediction based set-covering algorithm

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Algorithm 1 DOVE Algorithm (R, V, F)
1: I ← R.
                                                                                Considering
 2: U \leftarrow V
                                                                                vehicles' travel time
 3: P \leftarrow \emptyset
 4: while U \neq \emptyset do
       update S_i^* \leftarrow S_i for i \in I by pruning unsatisfied vehicles v
       such that \hat{t}_{p_v,i} < \gamma or t_{p_v,i} > \delta where v \in S_i.
       select a S_i^* \in F that maximizes |S_i^* \cap U| for i \in I
                                                                                    \rightarrow RN selection
       select a provider d_i \in S_i^* whose arrival time at RN i is
       minimum
     U \leftarrow U - S_i^*
     I \leftarrow I - \{i\}
                                                                                   Provider selection
     P \leftarrow P \cup \{(i, d_i)\}
11: end while
12: return P
                                                                                                    13/19
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DOVE Algorithm (3/3)

- DOVE+ algorithm (using multiple donations)
 - Enhanced DOVE algorithm to further reduce # of providers
 - (1) Select an S_i* to decide an OP that directly covers the maximum vehicles
 - (2) Find a provider that is the first vehicle reaching the selected OP
 - (3) Find additional consumers using RNs where a provider will pass (multiple donations)
 - (4) Repeat the steps (1)-(3)



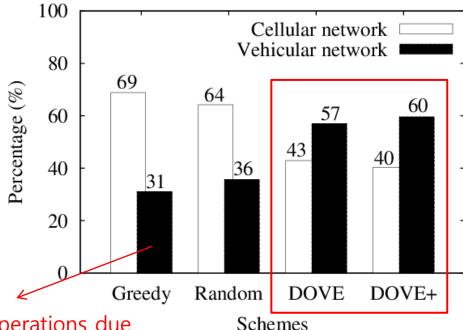
Simulation Environments

Simulation configuration	
Road network	The number of intersections is 49. The area of the road map is 8.25km×9km.
Communication range of DSRC [4]	Communication range $R = 200$ meters. Bandwidth of the DSRC = 25 Mbps.
Number of vehicles (N)	The number of vehicles moving within the road network. The default N is 300.
Vehicle speed (v)	$v \sim N(\mu_v, \sigma_v)$ where $\mu_v = \{20, 25,, 60\}$ MPH and $\sigma_v = 5$ MPH. The default (μ_v, σ_v) is $(40, 5)$ [5,6].
Deployment ratio (a)	The ratio a of the number of deployed RNs to the total number of intersections. The default a is 1.
Tolerance time (δ)	The maximum (tolerable) delay of vehicles. The default δ is 600 sec (i.e., 10 min) [7].
Cellular Communication	Cellular BW = 2.1 Mbps, file size = 12MB Cellular downloading time γ is 47.9 sec.
Comparison (RN selection algorithm)	DOVE algorithm, DOVE+ algorithm, Random selection, Greedy selection

Simulation Results (1/3)

- The percentage of offloading vehicles
 - In DOVE (DOVE+), more than half (i.e., 57%/60%) offload their traffic from the cellular network to the vehicular network
 - Only 31% (Greedy) and 36% (Random) of request vehicles take advantage of data offloading

 DOVE selects more effective OPs compared to Greedy and Random.

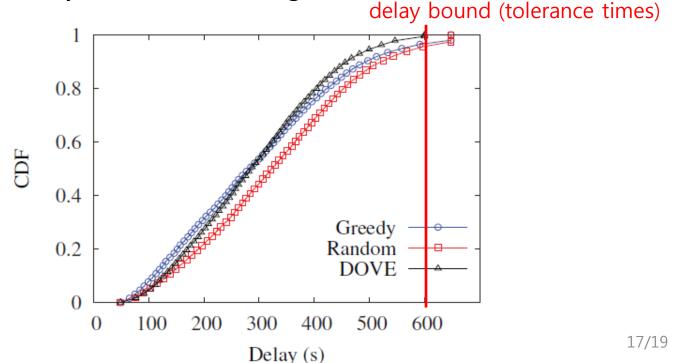


Failure of offloading operations due to absence of time consideration

Simulation Results (2/3)

- The content retrieval time
 - All the consumers using DOVE obtain the file within the delay bound(i.e., 600 seconds)
 - But, Greedy and Random show the non-negligible portion of consumers that exceed the delay bound
 - Greedy and Random show shorter content retrieval delay

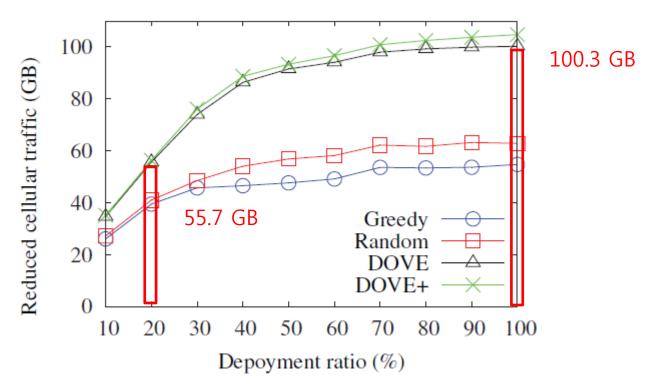
Due to early failure of offloading



Simulation Results (3/3)

Partial deployment

- The higher deployment ratio leads to the less usage of cellular links (all algorithms)
- RNs in only 20% of intersections can reduce about half of traffic reduction in the full deployment



Conclusion

- We propose data offloading framework (DOVE) for redundant traffic caused by in-vehicle data services
 - Utilizing vehicle trajectories
 - Formulating the selection of OPs as a set-covering problem
 - Proposing a DOVE algorithm to select OPs
- DOVE can provide cost effective offloading service with infrastructure nodes for the driving safety
 - DOVE reduces 57% of cellular link usage via OPs
 - DOVE can be used as one of solutions to resolve the mobile traffic explosion

References

- [1] M. Cha, H. Kwak, P. Rodriguez, Y.-Y. Ahn, and S. Moon, "I Tube, You Tube, Everybody Tubes: Analyzing the Worlds Largest User Generated Content Video System," in Proc. of ACM IMC, 2007.
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Q&A



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